

23 March 2004

THE COMMISSIONER OF PATENTS

Alexandria, VA 22313-1450

Sir:

In re application of: Kenneth Edward Hunt et al.

For: SELF-PROPELLED MOWER HAVING ENHANCED MANEUVERABILITY

DISCLOSURE STATEMENT

In compliance with 37 CFR 1.56 and guided by 37 CFR 1.97 - 1.99, applicants respectfully submit the following information including the cited documents on the attached form PTO-1449.

This information Disclosure Statement is filed as of the filing date of this application, which is within the statutory period of 37 CFR 1.97 (b) (1) where no fee is required. No explanation is required for the references in the English language, under 37 CFR 1.98 (a) (3) (i).

Respectfully submitted,


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Form PTO-1449

INFORMATION DISCLOSURE CITATION IN AN APPLICATION

(Use several sheets if necessary)

U.S. PATENT DOCUMENTS

Docket Number (Optional)

Application Number

16359D2-US

Applicant

Kenneth Edward Hunt et al.

Filing Date

23 March 2004

Group Art Unit

EXAMINER INITIAL	DOCUMENT NUMBER	DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATE
	4,119,900	10/1978	Kremnitz	318	587	
	6,604,348	08/2003	Hunt	56	10.6	
	2001/0047231	11/2001	Peless et al	701	23	
	2002/0023788	02/2002	Torrie et al	180	9.26	
	2002/0104300	08/2002	Hunt	56	10.6	
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	2003/0144774	07/2003	Trissel et al	701	23	
	2003/0226340	12/2003	Havermans et al	56	10.2	
	2003/0229425	12/2003	Miedema	701	1	
	2003/0229435	12/2003	Van der LELY	701	50	
	2004/0010343	01/2004	Dean	700	245	

FOREIGN PATENT DOCUMENTS

DOCUMENT NUMBER	DATE	COUNTRY	CLASS	SUBCLAS S	Translation YES NO

OTHER DOCUMENTS (Including Author, Title, Date, Pertinent Pages, Etc.)

	Dave Doding. Planetary Rovers Might Roam Better with an Elastic Loop Mobility System [online] June 22, 1998 [retrieved on 2004-03-10]. Retrieved from the Internet: <URL: http://science.msfc.nasa.gov/newhome/headlines/msad28apr98_1b.htm >.
	Autonomous Solutions, Inc. ODIS [online] [retrieved on 2003-12-01]. Retrieved from the Internet: <URL: http://autonomoussolutions.com/research/projects/odis.html >.
	The Robotics Institute. Lunar Rover Navigation 1996 System Architecture [online] Nov. 1996 [retrieved on 2004-03-10]. Retrieved from the Internet: <URL: http://www-2.cs.cmu.edu/~lri/architecture.shtml >.
	The Robotics Institute. The Navigation System [online] March 1995 [retrieved on 2004-03-10]. Retrieved from the Internet: <URL: http://www-2.cs.cmu.edu/afs/cs/project/lri/www/lrd/nav-navmap.html >.
	Williamson Labs. Much Mower [online] 1999 [Retrieved on 2003-12-01]. Retrieved from the Internet: <URL: http://www.williamson-labs.com/muchmower.htm >.

EXAMINER

DATE CONSIDERED

EXAMINER: Initial if citation considered, whether or not citation is in conformance with MPEP §609; Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to the applicant.